## **AMENDMENTS TO THE CLAIMS**

This listing of claims will replace all prior versions and listings of claims in the application.

## **Listing of Claims:**

- 1. (Withdrawn) A dispenser for fabricating a liquid crystal display panel, comprising:
- a syringe having a nozzle at one end and separated from a substrate;
- a vertical driving motor driving the syringe in a vertical direction;
- a contact type switch switching on/off the vertical driving motor depending on whether the nozzle and the substrate are in contact with each other; and
- a first sensor detecting an initial value between the nozzle and the substrate by switching on and off the contact type switch.
- 2. (Withdrawn) The dispenser of claim 1, wherein the first sensor comprises a laser displacement sensor.
  - 3. (Withdrawn) The dispenser of claim 1, wherein a sealant is stored in the syringe.
- 4. (Withdrawn) The dispenser of claim 1, wherein a liquid crystal is stored in the syringe.
  - 5. (Withdrawn) The dispenser of claim 1, wherein a liquid silver is stored in the syringe.
- 6. (Withdrawn) The dispenser of claim 1, wherein the vertical driving motor drives the syringe according to driving data inputted from a user through an input unit.
- 7. (Withdrawn) The dispenser of claim 6, wherein the input unit comprises one of a touch panel and a keyboard.
- 8. (Withdrawn) The dispenser of claim 1, further comprising a body supporting the syringe.

- 9. (Withdrawn) The dispenser of claim 1, further comprising a table on which the substrate is loaded.
- 10. (Withdrawn) The dispenser of claim 9, wherein the table is capable of horizontally moving in forward/backward and left/right directions.
- 11. (Previously Presented) A method for controlling a gap between a nozzle and a substrate by using a dispenser for fabricating a liquid crystal display panel, comprising:

lowering a body supporting a syringe having a nozzle at one end towards a substrate using a vertical driving motor, wherein the vertical driving motor drives the syringe according to driving data input from a user through an input unit which comprises one of a touch panel and a keyboard, wherein the lowering is performed at a first speed;

stopping the lowering when the nozzle contacts the substrate, wherein a contact type switch detects the nozzle contacting the substrate;

lifting up the body, wherein the contact type switch detects the nozzle being isolated from the substrate, wherein the lifting is performed at a second speed, and wherein the second speed is slower than the first speed;

detecting an initial value between the nozzle and the substrate when a state of the contact type switch is switched, wherein the initial value is a distance between the nozzle and the substrate when the nozzle is in contact with the substrate, and wherein the detecting the initial value is performed by a laser displacement sensor; and

lowering the body after detecting the initial value, so that the nozzle reaches a desired height from the initial value.

- 12. 14. (Cancelled)
- 15. (Original) The method of claim 11, wherein a sealant is stored in the syringe.
- 16. (Original) The method of claim 11, wherein a liquid crystal is stored in the syringe.

- 17. (Original) The method of claim 11, wherein a liquid silver is stored in the syringe.
- 18. (Previously Presented) A method for controlling a gap between a nozzle and a substrate, comprising:

lowering a body supporting a syringe having a nozzle at one end towards a substrate, wherein the lowering is performed at a first speed;

stopping the lowering when the nozzle contacts the substrate, wherein a contact type switch detects the nozzle contacting the substrate;

lifting up the body, wherein the contact type switch detects the nozzle being isolated from the substrate, wherein the lifting is performed at a second speed, and wherein the second speed is slower than the first speed;

detecting an initial value between the nozzle and the substrate when a state of the contact switch is switched, and wherein the detecting the initial value is performed by a laser displacement sensor; and

positioning the body after detecting the initial value so that the nozzle reaches a desired height from the initial value.

19. (Canceled)